# Detection of unknown boundaries and inclusions in elastic plates

## A. Morassi<sup>1</sup> E. Rosset<sup>2</sup> S. Vessella<sup>3</sup>

<sup>1</sup>Dipartimento di Ingegneria Civile e Architettura, Università di Udine.

<sup>2</sup>Dipartimento di Matematica e Geoscienze Università di Trieste

> <sup>3</sup>DIMAD Università di Firenze

#### 

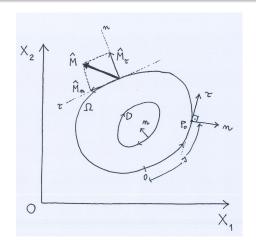
A. Morassi E. Rosset S. Vessella

# **KINDS OF DEFECTS:**

- Inclusions made of elastic material either softer or harder than the background
- Cavities
- Inaccessible portions of the boundary of the plate
- Rigid inclusions

・ロト ・ 理 ト ・ ヨ ト ・

-



$$\hat{M} = \hat{M}_{\tau} n + \hat{M}_{n} \tau = \hat{M}_{2} e_{1} + \hat{M}_{1} e_{2}, \quad \text{on } \partial\Omega, \quad \tau = e_{3} \times n$$

A. Morassi E. Rosset S. Vessella

Statical equilibrium problem when D is a rigid inclusion

$$\int div(div(\mathbb{P}\nabla^2 w)) = 0, \qquad \text{in } \Omega \setminus \overline{D},$$

$$(\mathbb{P}\nabla^2 w)n \cdot n = -\hat{M}_n, \qquad \text{on } \partial\Omega,$$

$$(BVP) \begin{cases} div(\mathbb{P}\nabla^2 w) \cdot n + ((\mathbb{P}\nabla^2 w)n \cdot \tau)_{,s} = (\hat{M}_{\tau})_{,s}, & \text{on } \partial\Omega, \\ w|_{\overline{D}} \in \mathcal{A}, \\ w^{e}, n = w^{i}, n, & \text{on } \partial D, \end{cases}$$

coupled with the equilibrium conditions

$$egin{aligned} (E) \int_{\partial D} \left( \operatorname{div}(\mathbb{P} 
abla^2 w) \cdot n + ((\mathbb{P} 
abla^2 w) n \cdot au)_s 
ight) g - ((\mathbb{P} 
abla^2 w) n \cdot n) g_{,n} = 0, \ orall g \in \mathcal{A}, \end{aligned}$$

$$\mathcal{A} = \{g(x_1, x_2) = ax_1 + bx_2 + c, a, b, c \in \mathbb{R}\}$$

A. Morassi E. Rosset S. Vessella

• 
$$\mathbb{P} = \frac{h^3}{12}\mathbb{C}$$
  
•  $\mathbb{C} \in L^{\infty}(\overline{\Omega}), C_{\alpha\beta\gamma\delta} = C_{\gamma\delta\alpha\beta} = C_{\gamma\delta\beta\alpha}, \quad \alpha, \beta, \gamma, \delta = 1, 2.$   
•  $\mathbb{C}$  strongly convex :

$$\exists \gamma > \mathbf{0} \mid \mathbb{C}(x) \mathbf{A} \cdot \mathbf{A} \geq \gamma |\mathbf{A}|^2,$$

for every 2 × 2 symmetric matrix *A* and for every  $x \in \overline{\Omega}$ .

- $\hat{M} \in H^{-\frac{1}{2}}(\partial\Omega, \mathbb{R}^2).$
- Compatibility conditions :  $\int_{\partial\Omega} \hat{M}_{\alpha} = 0, \ \alpha = 1, 2,$
- Ω, D simply connected bounded domains in ℝ<sup>2</sup> of class C<sup>1,1</sup>, D ⊂⊂ Ω.

# DIRECT PROBLEM

Problem (*BVP*) admits a weak solution  $w \in H^2(\Omega \setminus \overline{D})$ , which is determined up to the addition of an affine function. If we require

(NC) 
$$w = 0, w_{n} = 0$$
 on  $\partial D$ .

there exists a unique solution satisfying

$$\|w\|_{H^2(\Omega\setminus\overline{D})} \leq C\|\widehat{M}\|_{H^{-1/2}(\partial\Omega)}.$$

Let 
$$H = \{ v \in H^2(\Omega \setminus \overline{D}) \mid v = 0, v_{,n} = 0 \text{ on } \partial D \}$$

**Variational formulation** A weak solution to the mixed problem (BVP) - (NC) is a function  $w \in H$  satisfying

$$\int_{\Omega\setminus\overline{D}}\mathbb{P}\nabla^2 w\cdot\nabla^2 v=\int_{\partial\Omega}-\hat{M}_{\tau,s}v-\hat{M}_nv_{,n},\quad\forall v\in H.$$

## **INVERSE PROBLEM**

To determine the **unknown** rigid inclusion *D* from the additional measurement taken on an open portion  $\Gamma$  of  $\partial \Omega$  of the Dirichlet data  $\{w, w_{n}\}$ , that is from the Cauchy data on  $\Gamma$ :

$$(Cauchy) \begin{cases} w|_{\Gamma} \\ w_{,n}|_{\Gamma} \\ (\mathbb{P}\nabla^{2}w)n \cdot n|_{\Gamma} = -\widehat{M}_{n} \\ div(\mathbb{P}\nabla^{2}w) \cdot n + ((\mathbb{P}\nabla^{2}w)n \cdot \tau)_{,s}|_{\Gamma} = M_{\tau,s} \end{cases}$$

#### **APPLICATIONS**

Non-destructive testing for quality assessment of materials

A. Morassi E. Rosset S. Vessella

## HYPOTHESES FOR UNIQUENESS

- $(\widehat{M}_n, (\widehat{M}_\tau), s) \neq 0$
- The rigid inclusions D is of class  $C^{3,1}$ .
- The boundary measurements are taken on an open portion Γ of ∂Ω of class C<sup>3,1</sup>.
- The elasticity tensor C is of class C<sup>1,1</sup> and satisfies a dichotomy condition ensuring that the complex characteristic lines of the principal part of the operator have the same multiplicity everywhere (1 or 2), that is:

イロト 不得 とくほ とくほ とうほ

> (1) either  $\mathcal{D}(x) > 0, \ \forall x \in \mathbb{R}^2$ (2) or  $\mathcal{D}(x) = 0, \ \forall x \in \mathbb{R}^2$

 $\mathcal{D}(x)$  absolute value of the discriminant of p(x; (t, 1)), where  $p(x; \xi)$  is the symbol of the principal part of the operator.

**Class of Orthotropic materials:** through each point there pass three mutually orthogonal planes of elastic symmetry, which are parallel at all points.

- Any orthotropic material satisfy either (1) or (2)
- Isotropic material  $\Rightarrow \mathcal{D}(x) \equiv 0$
- There exist anisotropic orthotropic materials for which  $\mathcal{D}(x) \equiv 0$

**Remark.** The value of  $\mathcal{D}(x)$  cannot be interpreted as a measure of anisotropy.

A. Morassi E. Rosset S. Vessella

> (1) either  $\mathcal{D}(x) > 0, \ \forall x \in \mathbb{R}^2$ (2) or  $\mathcal{D}(x) = 0, \ \forall x \in \mathbb{R}^2$

 $\mathcal{D}(x)$  absolute value of the discriminant of p(x; (t, 1)), where  $p(x; \xi)$  is the symbol of the principal part of the operator.

**Class of Orthotropic materials:** through each point there pass three mutually orthogonal planes of elastic symmetry, which are parallel at all points.

- Any orthotropic material satisfy either (1) or (2)
- Isotropic material  $\Rightarrow \mathcal{D}(x) \equiv 0$
- There exist anisotropic orthotropic materials for which  $\mathcal{D}(x) \equiv 0$

**Remark.** The value of  $\mathcal{D}(x)$  cannot be interpreted as a measure of anisotropy.

A. Morassi E. Rosset S. Vessella

> (1) either  $\mathcal{D}(x) > 0, \ \forall x \in \mathbb{R}^2$ (2) or  $\mathcal{D}(x) = 0, \ \forall x \in \mathbb{R}^2$

 $\mathcal{D}(x)$  absolute value of the discriminant of p(x; (t, 1)), where  $p(x; \xi)$  is the symbol of the principal part of the operator.

**Class of Orthotropic materials:** through each point there pass three mutually orthogonal planes of elastic symmetry, which are parallel at all points.

- Any orthotropic material satisfy either (1) or (2)
- Isotropic material  $\Rightarrow \mathcal{D}(x) \equiv 0$
- There exist anisotropic orthotropic materials for which  $\mathcal{D}(x) \equiv 0$

**Remark.** The value of  $\mathcal{D}(x)$  cannot be interpreted as a measure of anisotropy.

A. Morassi E. Rosset S. Vessella

> (1) either  $\mathcal{D}(x) > 0, \ \forall x \in \mathbb{R}^2$ (2) or  $\mathcal{D}(x) = 0, \ \forall x \in \mathbb{R}^2$

 $\mathcal{D}(x)$  absolute value of the discriminant of p(x; (t, 1)), where  $p(x; \xi)$  is the symbol of the principal part of the operator.

**Class of Orthotropic materials:** through each point there pass three mutually orthogonal planes of elastic symmetry, which are parallel at all points.

- Any orthotropic material satisfy either (1) or (2)
- Isotropic material  $\Rightarrow \mathcal{D}(x) \equiv 0$
- There exist anisotropic orthotropic materials for which  $\mathcal{D}(x) \equiv 0$

**Remark.** The value of  $\mathcal{D}(x)$  cannot be interpreted as a measure of anisotropy.

A. Morassi E. Rosset S. Vessella

> (1) either  $\mathcal{D}(x) > 0, \ \forall x \in \mathbb{R}^2$ (2) or  $\mathcal{D}(x) = 0, \ \forall x \in \mathbb{R}^2$

 $\mathcal{D}(x)$  absolute value of the discriminant of p(x; (t, 1)), where  $p(x; \xi)$  is the symbol of the principal part of the operator.

**Class of Orthotropic materials:** through each point there pass three mutually orthogonal planes of elastic symmetry, which are parallel at all points.

- Any orthotropic material satisfy either (1) or (2)
- Isotropic material  $\Rightarrow \mathcal{D}(x) \equiv 0$
- There exist anisotropic orthotropic materials for which  $\mathcal{D}(x) \equiv 0$

**Remark.** The value of  $\mathcal{D}(x)$  cannot be interpreted as a measure of anisotropy.

A. Morassi E. Rosset S. Vessella

> (1) either  $\mathcal{D}(x) > 0, \ \forall x \in \mathbb{R}^2$ (2) or  $\mathcal{D}(x) = 0, \ \forall x \in \mathbb{R}^2$

 $\mathcal{D}(x)$  absolute value of the discriminant of p(x; (t, 1)), where  $p(x; \xi)$  is the symbol of the principal part of the operator.

**Class of Orthotropic materials:** through each point there pass three mutually orthogonal planes of elastic symmetry, which are parallel at all points.

- Any orthotropic material satisfy either (1) or (2)
- Isotropic material  $\Rightarrow \mathcal{D}(x) \equiv 0$
- There exist anisotropic orthotropic materials for which  $\mathcal{D}(x) \equiv 0$

**Remark.** The value of  $\mathcal{D}(x)$  cannot be interpreted as a measure of anisotropy.

A. Morassi E. Rosset S. Vessella

Theorem (A. Morassi, E.R., C.R. Mecanique 338, 2010) Let  $w_i$ , i = 1, 2, be the solutions to the normalized problem

$$(NP) \begin{cases} \operatorname{div}(\operatorname{div}(\mathbb{P}\nabla^2 w_i)) = 0, & \text{in } \Omega \setminus \overline{D_i}, \\ (\mathbb{P}\nabla^2 w_i)n \cdot n = -\hat{M}_n, & \text{on } \partial\Omega, \\ \operatorname{div}(\mathbb{P}\nabla^2 w_i) \cdot n + ((\mathbb{P}\nabla^2 w_i)n \cdot \tau)_{,s} = (\hat{M}_{\tau})_{,s}, & \text{on } \partial\Omega, \\ w_i = 0 & \text{on } \partial D_i, \\ w_{i,n} = 0 & \text{on } \partial D_i. \end{cases}$$

If for some  $g \in \mathcal{A}$ 

$$w_1 - w_2 = g$$
,  $(w_1 - w_2)_{,n} = g_{,n}$ , on  $\Gamma$ ,

then  $D_1 = D_2$ .

## **OTHER KINDS OF DEFECTS**

- CAVITIES → uniqueness with TWO measurements (Morassi, E. R., Vessella, Inverse Problems and Imaging, 2007)
- UNKNOWN BOUNDARIES → uniqueness with one measurement (A. Morassi, E. R., C.R. Mecanique, 2010)

**Math.** In both cases homogeneous Neumann b.c. on the boundary of the defect, but different geometry.

ヘロア 人間 アメヨア 人口 ア

## **OTHER KINDS OF DEFECTS**

- CAVITIES → uniqueness with TWO measurements (Morassi, E. R., Vessella, Inverse Problems and Imaging, 2007)
- UNKNOWN BOUNDARIES → uniqueness with one measurement (A. Morassi, E. R., C.R. Mecanique, 2010)

**Math.** In both cases homogeneous Neumann b.c. on the boundary of the defect, but different geometry.

・ロト ・ 理 ト ・ ヨ ト ・

# **OTHER KINDS OF DEFECTS**

- CAVITIES → uniqueness with TWO measurements (Morassi, E. R., Vessella, Inverse Problems and Imaging, 2007)
- UNKNOWN BOUNDARIES → uniqueness with one measurement (A. Morassi, E. R., C.R. Mecanique, 2010)

**Math.** In both cases homogeneous Neumann b.c. on the boundary of the defect, but different geometry.

・ロト ・ 理 ト ・ ヨ ト ・

# A PRIORI ASSUMPTIONS FOR STABILITY

- $\partial \Omega$  of class  $C^{2,1}$  with constants  $\rho_0$ ,  $M_0$
- |Ω| ≤ M<sub>1</sub>
- dist $(D, \partial \Omega) \ge \rho_0$
- $\partial D$  of class  $C^{3,1}$  with constants  $\rho_0$  ,  $M_0$
- $\widehat{M} \in L^2(\partial\Omega, \mathbb{R}^2), \, (\widehat{M}_n, (\widehat{M}_{\tau}), s) \not\equiv 0$
- $supp(\widehat{M}) \subset \Gamma, \Gamma \in C^{3,1}$
- $\partial \Omega \cap B_{\rho_0}(P_0) \subset \Gamma$ , for some  $P_0 \in \Gamma$

• 
$$\frac{\|\widehat{M}\|_{L^2}}{\|\widehat{M}\|_{H^{-1/2}}} \leq F$$

イロン 不得 とくほど 不良 とうほう

# A PRIORI ASSUMPTIONS FOR STABILITY

- $\partial \Omega$  of class  $C^{2,1}$  with constants  $\rho_0$  ,  $M_0$
- |Ω| ≤ M<sub>1</sub>
- dist $(D, \partial \Omega) \ge \rho_0$
- $\partial D$  of class  $C^{3,1}$  with constants  $\rho_0$  ,  $M_0$
- $\widehat{M} \in L^2(\partial\Omega, \mathbb{R}^2), \, (\widehat{M}_n, (\widehat{M}_{\tau}), s) \neq 0$
- $\operatorname{supp}(\widehat{M}) \subset \Gamma, \Gamma \in C^{3,1}$
- $\partial \Omega \cap B_{\rho_0}(P_0) \subset \Gamma$ , for some  $P_0 \in \Gamma$

• 
$$\frac{\|\widehat{M}\|_{L^2}}{\|\widehat{M}\|_{H^{-1/2}}} \leq F$$

- $\|\mathbb{C}\|_{\mathcal{C}^{1,1}}(\mathbb{R}^2) \leq M$
- $\mathbb{C}A \cdot A \geq \gamma |A|^2$ ,  $\forall$  symmetric 2 × 2 matrix A
- Dichotomy condition:

$$\begin{array}{ll} \text{either} \quad \mathcal{D}(x) > 0, \ \forall x \in \mathbb{R}^2 \ (\delta_1 = \min_{\mathbb{R}^2} \mathcal{D}) \\ \\ \text{or} \quad \mathcal{D}(x) = 0, \ \forall x \in \mathbb{R}^2 \end{array}$$

where  $\mathcal{D}(x)$  is the discriminant of the polynomial p(x; (t, 1)), where  $p(x; \xi)$  is the symbol of the principal part of the operator.

イロン 不得 とくほど 不良 とうほう

Theorem (Stability, A. Morassi, E. R., S. Vessella, SIAM J. Math. Anal. 2012)

Let  $w_i \in H^2(\Omega \setminus \overline{D_i})$  be the solutions to (NP), i = 1, 2. If, for some  $g \in A$ ,

$$\|w_1 - w_2 - g\|_{L^2(\Gamma)} + \|(w_1 - w_2), n - g, n)\|_{L^2(\Gamma)} \le \epsilon_1$$

then

$$d_{\mathcal{H}}(\overline{D_1},\overline{D_2}) \leq C(\log|\log\epsilon|)^{-\eta},$$

for every  $\epsilon$ ,  $0 < \epsilon < e^{-1}$ , where C > 0,  $\eta$ ,  $0 < \eta \le 1$ , are constants only depending on the a priori data.

# Stability results in other contexts

- Electrical conductors: log type stability estimate for perfectly insulating and for perfectly conducting inclusions n = 2: Bukhgeim, Cheng, Yamamoto 1998, 1999, 2000, Beretta, Vessella 1998, Rondi 1999, Alessandrini, Rondi 2001;  $n \ge 2$ : Alessandrini, Beretta, R., Vessella, 2000
- Thermic conductors: log type stability estimate for solidification fronts and cavities Canuto, R., Vessella, 2002

# Stability results in other contexts

- Electrical conductors: log type stability estimate for perfectly insulating and for perfectly conducting inclusions n = 2:
   Bukhgeim, Cheng, Yamamoto 1998, 1999, 2000, Beretta, Vessella 1998, Rondi 1999, Alessandrini, Rondi 2001; n ≥ 2:
   Alessandrini, Beretta, R., Vessella, 2000
- Thermic conductors: log type stability estimate for solidification fronts and cavities Canuto, R., Vessella, 2002

III The log rate of convergence is optimal Mandache, 2001
Alessandrini, Rondi, 2001
Di Cristo, Rondi, 2003
Di Cristo, Rondi, Vessella, 2006

 isotropic elastic bodies: log-log - type estimate for cavities and for rigid inclusions Morassi, E. R., 2004, 2009

**Remark** The weaker rate of convergence in elastostatics is due to the lack of quantitative estimates of unique continuation at the boundary for solutions satisfying homogeneous Neumann/Dirichlet boundary conditions.

・ロト ・ 同ト ・ ヨト ・ ヨト

III The log rate of convergence is optimal Mandache, 2001
Alessandrini, Rondi, 2001
Di Cristo, Rondi, 2003
Di Cristo, Rondi, Vessella, 2006

 isotropic elastic bodies: log-log - type estimate for cavities and for rigid inclusions Morassi, E. R., 2004, 2009

**Remark** The weaker rate of convergence in elastostatics is due to the lack of quantitative estimates of unique continuation at the boundary for solutions satisfying homogeneous Neumann/Dirichlet boundary conditions.

・ロト ・ 同ト ・ ヨト ・ ヨト

III The log rate of convergence is optimal Mandache, 2001
Alessandrini, Rondi, 2001
Di Cristo, Rondi, 2003
Di Cristo, Rondi, Vessella, 2006

 isotropic elastic bodies: log-log - type estimate for cavities and for rigid inclusions Morassi, E. R., 2004, 2009

**Remark** The weaker rate of convergence in elastostatics is due to the lack of quantitative estimates of unique continuation at the boundary for solutions satisfying homogeneous Neumann/Dirichlet boundary conditions.

・ロ・ ・ 四・ ・ ヨ・ ・ ヨ・

# MATHEMATICAL TOOLS FOR UNIQUENESS

• Regularity of solutions

For every solution *w* to the normalized problem (NP),  $w \in C^1$  up to  $\partial D$ the b.c. at  $\partial D$  hold in the classical sense.

• Three spheres inequality

- Weak Unique Continuation Property of the solution. If  $w \equiv 0$  in some open nonempty subset of  $\Omega \setminus \overline{D}$ , then  $w \equiv 0$  in  $\Omega \setminus \overline{D}$ .
- Uniqueness for the Cauchy problem

A. Morassi E. Rosset S. Vessella Detection of unknown boundaries and inclusions in elastic plates

# MATHEMATICAL TOOLS FOR UNIQUENESS

• Regularity of solutions

For every solution *w* to the normalized problem (NP),  $w \in C^1$  up to  $\partial D$ the b.c. at  $\partial D$  hold in the classical sense.

• Three spheres inequality

- Weak Unique Continuation Property of the solution. If w ≡ 0 in some open nonempty subset of Ω \ D
   , then w ≡ 0
   in Ω \ D
   .
- Uniqueness for the Cauchy problem

A. Morassi E. Rosset S. Vessella Detection of unknown boundaries and inclusions in elastic plates

# MATHEMATICAL TOOLS FOR UNIQUENESS

#### • Regularity of solutions

For every solution *w* to the normalized problem (NP),  $w \in C^1$  up to  $\partial D$ the b.c. at  $\partial D$  hold in the classical sense.

• Three spheres inequality

# ₩

- Weak Unique Continuation Property of the solution. If  $w \equiv 0$  in some open nonempty subset of  $\Omega \setminus \overline{D}$ , then  $w \equiv 0$  in  $\Omega \setminus \overline{D}$ .
- Uniqueness for the Cauchy problem

# MATHEMATICAL TOOLS FOR UNIQUENESS

#### • Regularity of solutions

For every solution *w* to the normalized problem (NP),  $w \in C^1$  up to  $\partial D$ the b.c. at  $\partial D$  hold in the classical sense.

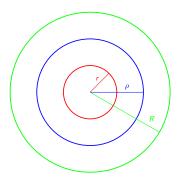
• Three spheres inequality

# ∜

- Weak Unique Continuation Property of the solution. If  $w \equiv 0$  in some open nonempty subset of  $\Omega \setminus \overline{D}$ , then  $w \equiv 0$  in  $\Omega \setminus \overline{D}$ .
- Uniqueness for the Cauchy problem

#### THREE SPHERES INEQUALITY

$$\int_{\boldsymbol{B}_{\rho}} |\nabla^2 \boldsymbol{w}|^2 \leq C \left(\int_{\boldsymbol{B}_{r}} |\nabla^2 \boldsymbol{w}|^2\right)^{\theta} \left(\int_{\boldsymbol{B}_{R}} |\nabla^2 \boldsymbol{w}|^2\right)^{1-\theta}$$



A. Morassi E. Rosset S. Vessella

Detection of unknown boundaries and inclusions in elastic plates

(日本)(日本)

∃ <2 <</p>

# MATHEMATICAL TOOLS FOR STABILITY

## • Regularity of solutions

For every solution *w* to the normalized problem (NP),  $w \in H^4$  in a nbhd of  $\partial D$  $w \in C^{1,1}$  up to  $\partial D$ 

• Three spheres inequality

#### • Stability for the Cauchy problem

Lipschitz Propagation of smallness estimate

ヘロア 人間 アメヨア 人口 ア

# MATHEMATICAL TOOLS FOR STABILITY

## • Regularity of solutions

For every solution *w* to the normalized problem (NP),  $w \in H^4$  in a nbhd of  $\partial D$  $w \in C^{1,1}$  up to  $\partial D$ 

• Three spheres inequality

#### • Stability for the Cauchy problem

Lipschitz Propagation of smallness estimate

ヘロア 人間 アメヨア 人口 ア

## MATHEMATICAL TOOLS FOR STABILITY

## • Regularity of solutions

For every solution *w* to the normalized problem (NP),  $w \in H^4$  in a nbhd of  $\partial D$  $w \in C^{1,1}$  up to  $\partial D$ 

• Three spheres inequality

#### ₩

#### • Stability for the Cauchy problem

Lipschitz Propagation of smallness estimate

ヘロン ヘアン ヘビン ヘビン

# MATHEMATICAL TOOLS FOR STABILITY

#### • Regularity of solutions

For every solution *w* to the normalized problem (NP),  $w \in H^4$  in a nbhd of  $\partial D$  $w \in C^{1,1}$  up to  $\partial D$ 

• Three spheres inequality

#### ₩

- Stability for the Cauchy problem
- Lipschitz Propagation of smallness estimate

ヘロン ヘアン ヘビン ヘビン

## Lipschitz propagation of smallness

Let  $w \in H^2(\Omega \setminus \overline{D})$  be a solution to the normalized problem (NP). There exists s > 1 (only depending on  $\gamma_0$ , M,  $\delta_1$ ,  $M_0$ ) s.t.  $\forall \rho > 0$  and  $\forall \overline{x} \in (\Omega \setminus \overline{D})_{s\rho}$  we have

$$(LPS) \qquad \qquad \int_{B_{\rho}(\overline{x})} |\nabla^2 w|^2 \geq \frac{C}{\exp\left[A\rho^{-B}\right]} \int_{(\Omega \setminus \overline{D})} |\nabla^2 w|^2,$$

where A > 0, B > 0 and C > 0 only depend on the a-priori data.

・ロト ・ 理 ト ・ ヨ ト ・

# "INTERMEDIATE CASE": ELASTIC INCLUSIONS

The inclusion  ${\it D}$  is made by elastic material with strongly convex tensor  $\widetilde{\mathbb{C}}$ 

Uniqueness results not available

• Alternative approach: estimates of the area of the inclusion

# "INTERMEDIATE CASE": ELASTIC INCLUSIONS

The inclusion  ${\it D}$  is made by elastic material with strongly convex tensor  $\widetilde{\mathbb{C}}$ 

- Uniqueness results not available
- Alternative approach: estimates of the area of the inclusion

# "INTERMEDIATE CASE": ELASTIC INCLUSIONS

The inclusion  ${\it D}$  is made by elastic material with strongly convex tensor  $\widetilde{\mathbb{C}}$ 

- Uniqueness results not available
- Alternative approach: estimates of the area of the inclusion

・ロット (雪) ( ) ( ) ( ) ( )

## **JUMP CONDITION**

$$\exists \ \delta > 0 \ \text{s.t.} \ \text{either} \ (\widetilde{\mathbb{C}} - \mathbb{C}) \ge \delta \mathbb{C}, \quad \text{or} \ (\mathbb{C} - \widetilde{\mathbb{C}}) \ge \delta \mathbb{C}.$$

### FATNESS CONDITION

*D* measurable such that here exists  $h_1 > 0$  s.t.

$$area(D_{h_1}) \geq \frac{1}{2}area(D),$$

where  $D_{h_1} = \{x \in D \mid dist(x, \partial D) > h_1\}.$ 

## **JUMP CONDITION**

$$\exists \ \delta > 0 \text{ s.t. either } (\widetilde{\mathbb{C}} - \mathbb{C}) \ge \delta \mathbb{C}, \quad \text{or } (\mathbb{C} - \widetilde{\mathbb{C}}) \ge \delta \mathbb{C}.$$

## **FATNESS CONDITION**

*D* measurable such that here exists  $h_1 > 0$  s.t.

$$area(D_{h_1}) \geq \frac{1}{2}area(D),$$

where  $D_{h_1} = \{x \in D \mid dist(x, \partial D) > h_1\}.$ 

イロト 不得 トイヨト イヨト 二日 二

Let  $w \in H^2(\Omega)$  be the solution to the equilibrium problem when the inclusion *D* is present

$$\int div(div((\chi_{\Omega \setminus D} \mathbb{P} + \chi_D \widetilde{\mathbb{P}}) \nabla^2 w)) = 0, \qquad \text{in } \Omega,$$

$$\begin{cases} P \\ div(\mathbb{P}\nabla^2 w)n \cdot n = -M_n, & \text{on } \partial\Omega, \\ div(\mathbb{P}\nabla^2 w) \cdot n + ((\mathbb{P}\nabla^2 w)n \cdot \tau), s = (\hat{M}_{\tau}), s, & \text{on } \partial\Omega, \end{cases}$$

normalized by the conditions

$$\int_{\Omega} w = 0, \quad \int_{\Omega} \nabla w = 0.$$

ヘロン ヘアン ヘビン ヘビン

3

Let  $w_0 \in H^2(\Omega)$  be the solution to the equilibrium problem when the inclusion is absent

$$\int div(div(\mathbb{P}\nabla^2 w_0)) = 0, \qquad \text{in }\Omega,$$

$$(P_0) \begin{cases} (\mathbb{P}\nabla^2 w_0) n \cdot n = -\hat{M}_n, & \text{on } \partial\Omega, \\ div(\mathbb{P}\nabla^2 w_0) \cdot n + ((\mathbb{P}\nabla^2 w_0) n \cdot \tau)_{,s} = (\hat{M}_{\tau})_{,s}, & \text{on } \partial\Omega, \end{cases}$$

normalized by the conditions

$$\int_{\Omega} w_0 = 0, \quad \int_{\Omega} \nabla w_0 = 0.$$

イロト 不得 トイヨト イヨト 二日 二

Works exerted by  $\widehat{M}$  when *D* is present and absent, respectively:

$$\begin{split} W &= \int_{\Omega} (\mathbb{P} + (\widetilde{\mathbb{P}} - \mathbb{P})\chi_D) \nabla^2 w \cdot \nabla^2 w = - \int_{\partial \Omega} \widehat{M}_{\tau,s} w + \widehat{M}_n w_{,n} \\ W_0 &= \int_{\Omega} \mathbb{P} \nabla^2 w_0 \cdot \nabla^2 w_0 = - \int_{\partial \Omega} \widehat{M}_{\tau,s} w_0 + \widehat{M}_n w_{0,n} \\ &= \frac{|W - W_0|}{W_0} \quad \text{normalized work gap} \end{split}$$

A. Morassi E. Rosset S. Vessella Detection of unknown boundaries and inclusions in elastic plates

イロト 不得 トイヨト イヨト 二日 二

Theorem (Size estimates, A. Morassi, E.R., S. Vessella, DCDS S 6, 2013)

Let  $\mathbb C$  satisfy the dichotomy condition.

$$C_1rac{|m{W}-m{W}_0|}{m{W}_0}\leq \textit{area}(D)\leq C_2rac{|m{W}-m{W}_0|}{m{W}_0}$$

**Remark:** The fatness condition is not needed for the lower bound. If the background material is isotropic (or  $\mathcal{D}(x) \equiv 0$ ) a (weaker) upper estimate holds without fatness condition

$$\mathit{area}(D) \leq C_2 \left( rac{|W-W_0|}{W_0} 
ight)^{rac{1}{
ho}},$$

where p > 1. (A. Morassi, E.R., S. Vessella, Inverse Problems 25, 2009)

A. Morassi E. Rosset S. Vessella

Detection of unknown boundaries and inclusions in elastic plates

Theorem (Size estimates, A. Morassi, E.R., S. Vessella, DCDS S 6, 2013)

Let  $\mathbb C$  satisfy the dichotomy condition.

$$C_1 rac{|\mathit{W} - \mathit{W}_0|}{\mathit{W}_0} \leq \mathit{area}(\mathit{D}) \leq C_2 rac{|\mathit{W} - \mathit{W}_0|}{\mathit{W}_0}$$

**Remark:** The fatness condition is not needed for the lower bound. If the background material is isotropic (or  $\mathcal{D}(x) \equiv 0$ ) a (weaker) upper estimate holds without fatness condition

$$area(D) \leq C_2 \left( rac{|\mathit{W} - \mathit{W}_0|}{\mathit{W}_0} 
ight)^{rac{1}{p}}$$

where p > 1. (A. Morassi, E.R., S. Vessella, Inverse Problems 25, 2009)

### Size estimates for estreme inclusions

## (cavities and rigid inclusions)

**Upper Bounds:** same results **Lower bounds:** under additional assumptions on the regularity of the defect, a weaker estimate is derived

$$area(D) \ge C_2 \left( rac{|W - W_0|}{W_0} 
ight)^2$$

(A. Morassi, E.R., S. Vessella, J. Inverse III Posed Problems 2013, review paper)

A. Morassi E. Rosset S. Vessella Detection of unknown boundaries and inclusions in elastic plates

#### Size estimates for estreme inclusions

## (cavities and rigid inclusions)

#### Upper Bounds: same results

**Lower bounds:** under additional assumptions on the regularity of the defect, a weaker estimate is derived

$$area(D) \ge C_2 \left( rac{|W - W_0|}{W_0} 
ight)^2$$

(A. Morassi, E.R., S. Vessella, J. Inverse III Posed Problems 2013, review paper)

A. Morassi E. Rosset S. Vessella Detection of unknown boundaries and inclusions in elastic plates

### Size estimates for estreme inclusions

## (cavities and rigid inclusions)

Upper Bounds: same results

**Lower bounds:** under additional assumptions on the regularity of the defect, a weaker estimate is derived

$$area(D) \geq C_2 \left( rac{|W - W_0|}{W_0} 
ight)^2,$$

(A. Morassi, E.R., S. Vessella, J. Inverse III Posed Problems 2013, review paper)

## **OPEN PROBLEMS AND DIRECTIONS OF FUTURE RESEARCH**

- Stability estimates for cavities and unknown portions of the boundary
- Optimality of the log-log stability for anisotropic materials?
- Strong unique continuation at the boundary for isotropic plates, in order to get optimal stability estimates

## **OPEN PROBLEMS AND DIRECTIONS OF FUTURE RESEARCH**

- Stability estimates for cavities and unknown portions of the boundary
- Optimality of the log-log stability for anisotropic materials?
- Strong unique continuation at the boundary for isotropic plates, in order to get optimal stability estimates

## **OPEN PROBLEMS AND DIRECTIONS OF FUTURE RESEARCH**

- Stability estimates for cavities and unknown portions of the boundary
- Optimality of the log-log stability for anisotropic materials?
- Strong unique continuation at the boundary for isotropic plates, in order to get optimal stability estimates

## **OPEN PROBLEMS AND DIRECTIONS OF FUTURE RESEARCH**

- Stability estimates for cavities and unknown portions of the boundary
- Optimality of the log-log stability for anisotropic materials?
- Strong unique continuation at the boundary for isotropic plates, in order to get optimal stability estimates