## Mahalanobis distances on factor structured data

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- MD on factor structured data
- 2 Definitions and assumptions
- Oistributional properties
- 4 Contaminated data
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## Background of Mahalanobis distance

Mahalanobis distance (MD) was proposed by Mahalanobis (1936). It is used for measuring the distance between two random vectors or one random vector and its mean vector. It is widely used in many areas such as cluster analysis; discriminant analysis (Fisher; 1940); assessing multivariate normality (Mardia; 1974; Mardia et al.; 1980; Mitchell and Krzanowski; 1985; Holgersson and Shukur; 2001); hypothesis testing and outlier detecting (Wilks; 1963; Mardia et al.; 1980).

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#### Backgrounds

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## Definition of Mahalanobis distance

#### The definition of Mahalanobis distance is given as follows,

#### Definition 1

Let  $\mathbf{X}_i : p \times 1$  be a random vector such that  $E[\mathbf{X}_i] = \mu_{p \times 1}$  and  $E[(\mathbf{X}_i - \mu)(\mathbf{X}_i - \mu)'] = \mathbf{\Sigma}_{p \times p}$  for i = 1, ..., n. Then we make the following definition:

$$D_{ii} := (\mathbf{X}_i - \boldsymbol{\mu})' \boldsymbol{\Sigma}^{-1} (\mathbf{X}_i - \boldsymbol{\mu}).$$
 (1)

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# Advantages of MD

The Mahalanobis distance which includes the covariance matrix is linear transformation invariant.

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# Background of factor model

Factor model is widely applied in many researches on the unobserved measurements. For example, the arbitrage pricing theory (Ross; 1976) based on the assumption that asset returns follow a factor structure. In consumer theory, factor analysis shows that utility maximizing could be described by at most three factors (Gorman et al.; 1981; Lewbel; 1991). In desegregate business cycle analysis, the factor model is used to identify the common and specific shocks that drive a country's economy (Gregory and Head; 1999; Bai; 2003).

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The combination of the factor model and Mahalanobis distance offers an option for both approximation of the structure of covariance and measuring the distance between observations at the same time. The balance between simplicity of structure and information offers a good method for the dependent structured data. In this presentation, we only concern the detection of outlier.

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## Definition of factor model

#### Definition 2

Let  $\mathbf{x} \sim N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$ , be the  $\boldsymbol{p} \times 1$  random observations with mean  $\boldsymbol{\mu}$  and covariance matrix  $\boldsymbol{\Sigma}$ . The factor model could be represented as

$$\mathbf{x} - \boldsymbol{\mu}_{(p \times 1)} = \mathbf{L}_{(p \times m)} \mathbf{F}_{(m \times 1)} + \boldsymbol{\varepsilon}_{(p \times 1)},$$

where **x** is the observed date (p > m),  $\mu$  the corresponding expectation , **L** the factor loadings and **F** is a  $m \times 1$  vector of factor scores.

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Assumptions of factor model

Beside the definition of factor model above, we need some more assumptions as follows.

#### Definition 3

Let  $E(\mathbf{F}) = \mathbf{0}$ ,  $Cov(\mathbf{F}) = \mathbf{I}_{m \times m}$  and  $E(\varepsilon) = \mathbf{0}$ . As defined above, assume  $\varepsilon \sim N(\mathbf{0}_{p \times 1}, \Psi)$ , where  $\Psi$  is a diagonal matrix and  $\mathbf{F} \sim N(\mathbf{0}_{m \times 1}, \mathbf{I})$  are distributed independently  $(Cov(\varepsilon, \mathbf{F}) = \mathbf{0})$ .

## Definitions of MDs on factor model

#### Definition 4

The MD on **F** part is

$$D(\mathbf{F}_i) = \mathbf{F}_i' \operatorname{cov}(\mathbf{F}_i)^{-1} \mathbf{F}_i = \mathbf{F}_i' \mathbf{F}_i,$$

while for the  $\varepsilon$  part, the MD is

$$D(\varepsilon_i) = \varepsilon_i{}'\Psi^{-1}\varepsilon_i.$$

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## Definitions of MDs on factor model

#### Definition 5

The MDs for the estimated factor scores and error are:

$$D\left(\hat{\mathbf{F}}_{i}\right) = \hat{\mathbf{F}}_{i}^{\prime} cov(\hat{\mathbf{F}}_{i})^{-1} \hat{\mathbf{F}}_{i} \text{ and } D\left(\hat{\varepsilon}_{i}\right) = \hat{\varepsilon}_{i}^{\prime} \hat{\Psi}^{-1} \hat{\varepsilon}_{i}.$$

where  $\hat{\mathbf{F}}_i = \hat{\mathbf{L}}' \mathbf{S}^{-1} (\mathbf{x}_i - \bar{\mathbf{x}})$  is the estimated factor scores from the regression method (Johnson and Wichern; 2002).

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## Joint distribution of seperated MDs

#### Proposition 1

The joint distribution of  $D(\mathbf{F}_i)$  and  $D(\varepsilon_i)$  is,

$$Z = \begin{bmatrix} D(\mathbf{F}_i) \\ D(\varepsilon_i) \end{bmatrix} \sim \begin{bmatrix} \chi^2_{(m)} \\ \chi^2_{(p)} \end{bmatrix}, \text{ cov } (Z) = \begin{bmatrix} 2m & 0 \\ 0 & 2p \end{bmatrix}.$$

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## Joint distribution of seperated MDs

#### Proposition 2

The asymptotic distributions of the MD under the factor model with an unknown factor structure is

$$\hat{\mathbf{Y}} = \begin{bmatrix} D\left(\hat{\mathbf{F}}_{i}\right) \\ D\left(\hat{\varepsilon}_{i}\right) \end{bmatrix} \stackrel{\ell}{\rightarrow} \begin{bmatrix} \chi_{(m)}^{2} \\ \chi_{(p)}^{2} \end{bmatrix}, \text{ cov } \left(\hat{\mathbf{Y}}\right) = \begin{bmatrix} 2m & 0 \\ 0 & 2p \end{bmatrix}.$$

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## Definitions of contaminated data

#### Definition 6

Assuming two kinds of outliers are interested: (i) an additive outlier in  $\varepsilon_i$  and (ii) an additive outlier in  $\mathbf{F}_i : m \times 1$ . The corresponding definitions are given as follows (assuming known mean):

(i) 
$$\mathbf{X}_i = \mathbf{LF}_i + arepsilon_i + \delta_i, \delta_i = \mathbf{0}, orall_{i 
eq k}, \delta_i : p imes 1$$
 and  $\delta_k \, ' \delta_k = 1$ .

(ii) 
$$\mathbf{X}_i = \mathbf{L} (\mathbf{F}_i + \delta_i) + \varepsilon_i, \delta_i = \mathbf{0}, \forall_{i \neq k}, \delta_k : m \times 1.$$

## Contaminated data

Let  $d_{\delta j}$ , j = 1, 2 be the MDs for the two kinds of outliers, and let  $\mathbf{S} = n^{-1} \sum_{i=1}^{n} (\mathbf{LF}_i + \varepsilon_i) (\mathbf{LF}_i + \varepsilon_i)'$  be the sample covariance matrix with known mean. To simplify calculations, let  $\delta_k \perp \mathbf{F}_i$  and  $\delta_k \perp \varepsilon_i$  by assumption, so that they are not only uncorrelated but also orthogonal. The following expressions separate the contaminated and un-contaminated parts of the MD: Definitions and assumptions Distributional properties Contaminated data References

## Contaminated data

#### Proposition 3

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For case (i),  

$$d_{\delta 1} = \begin{cases} d_{ii} & i \neq k \\ d_{\delta 1} = \begin{cases} d_{kk} - \frac{n(1 - \mathbf{x}_k' n^{-1} \mathbf{S}^{-1} \delta_k)^2}{1 + \delta'_k n^{-1} \mathbf{S}^{-1} \delta_k} + n & i = k \end{cases}$$

For case (ii),  

$$d_{\delta 2} = \begin{cases} d_{ii} & i \neq k \\ d_{kk} - \frac{n(1 - \mathbf{x}_k' n^{-1} \mathbf{S}^{-1} \mathbf{L} \delta_k)^2}{1 + \delta_k' \mathbf{L}' n^{-1} \mathbf{S}^{-1} \mathbf{L} \delta_k} + n. & i = k \end{cases}$$

where  $d_{ii} = n\mathbf{x}_i'\mathbf{W}^{-1}\mathbf{x}_i = \mathbf{x}_i'\mathbf{S}^{-1}\mathbf{x}_i$ .

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We implicate the results on a data setting which is consisted by the monthly closing stock prices from ten companies.

The companies are Exxon Mobil Corp., Chevron Corp., Apple Inc., General Electric Co., Wells Fargo Co., Procter Gamble Co., Microsoft Corp., Johnson & Johnson, Google Inc., Johnson Control Inc. They follow by the order of variables.

### Dataset

We modified the closing prices into the monthly return rate (r),  $r = \frac{y_t - y_{t-1}}{y_{t-1}},$ 

where  $y_t$  stands for the closing price in the *t*th month. The whole analysis based on the returns on the stock prices.

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## Boxplot



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Figure: The boxplot of error terms.

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Figure: The boxplot of factor scores.

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